

CS4641B Machine Learning

Lecture 06: Optimization

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Outline

- Overview
- Unconstrained and constrained optimization
- Lagrange multipliers and KKT conditions
- Gradient descent

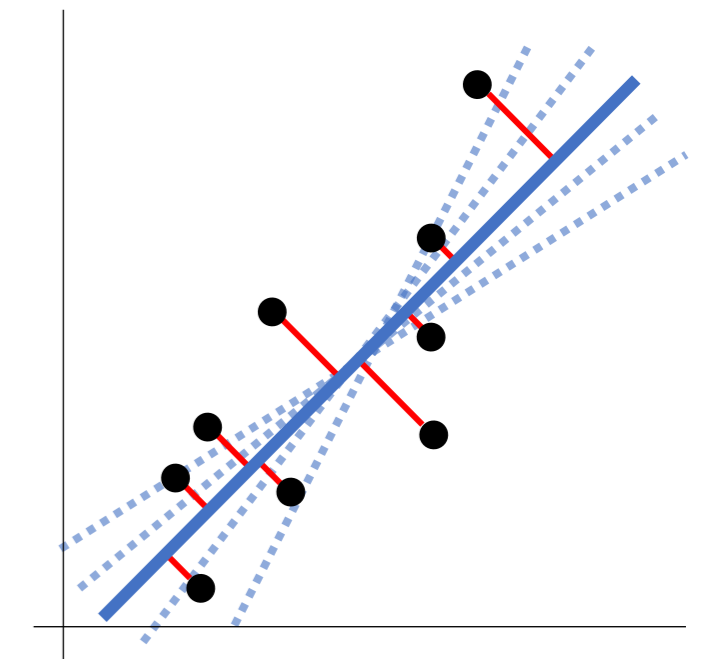
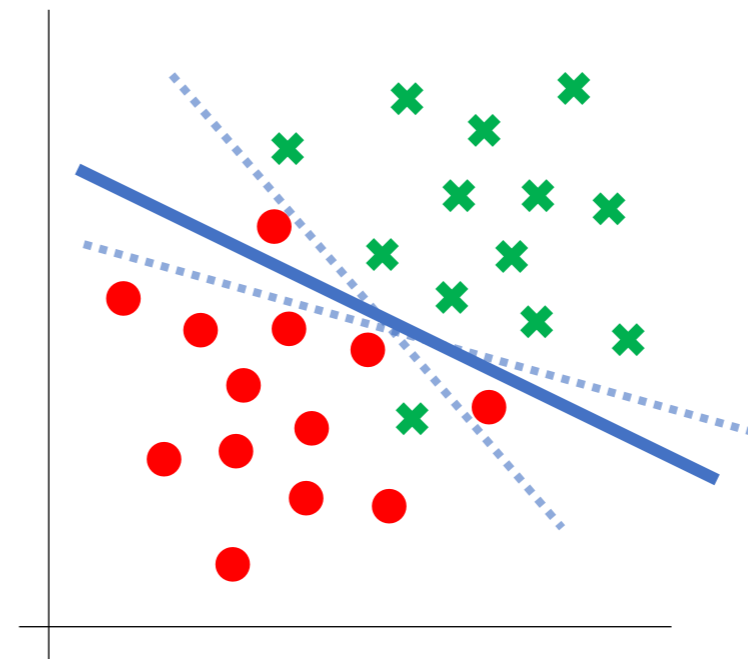
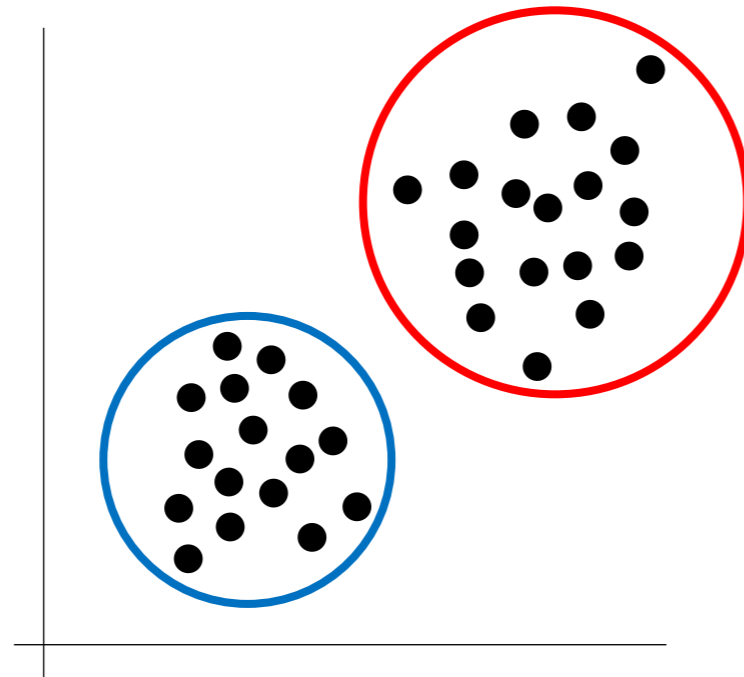
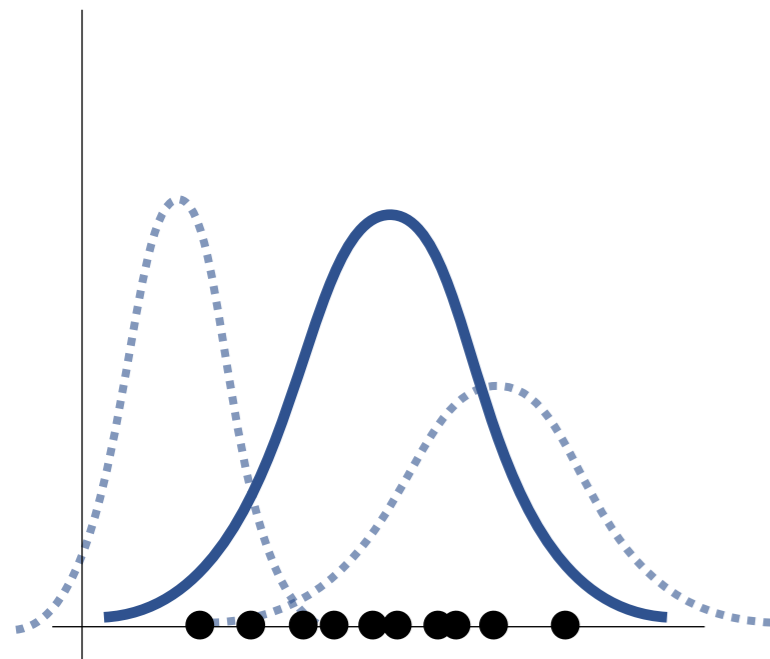
Complementary reading: Bishop PRML – Appendix E

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- **Overview**
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Why optimization?

- Machine learning and pattern recognition algorithms often focus on the minimization or maximization of a quantity
 - Likelihood of a distribution given a dataset
 - Distortion measure in clustering analysis
 - Misclassification error while predicting labels
 - Square distance error for a real value prediction task



Basic optimization problem

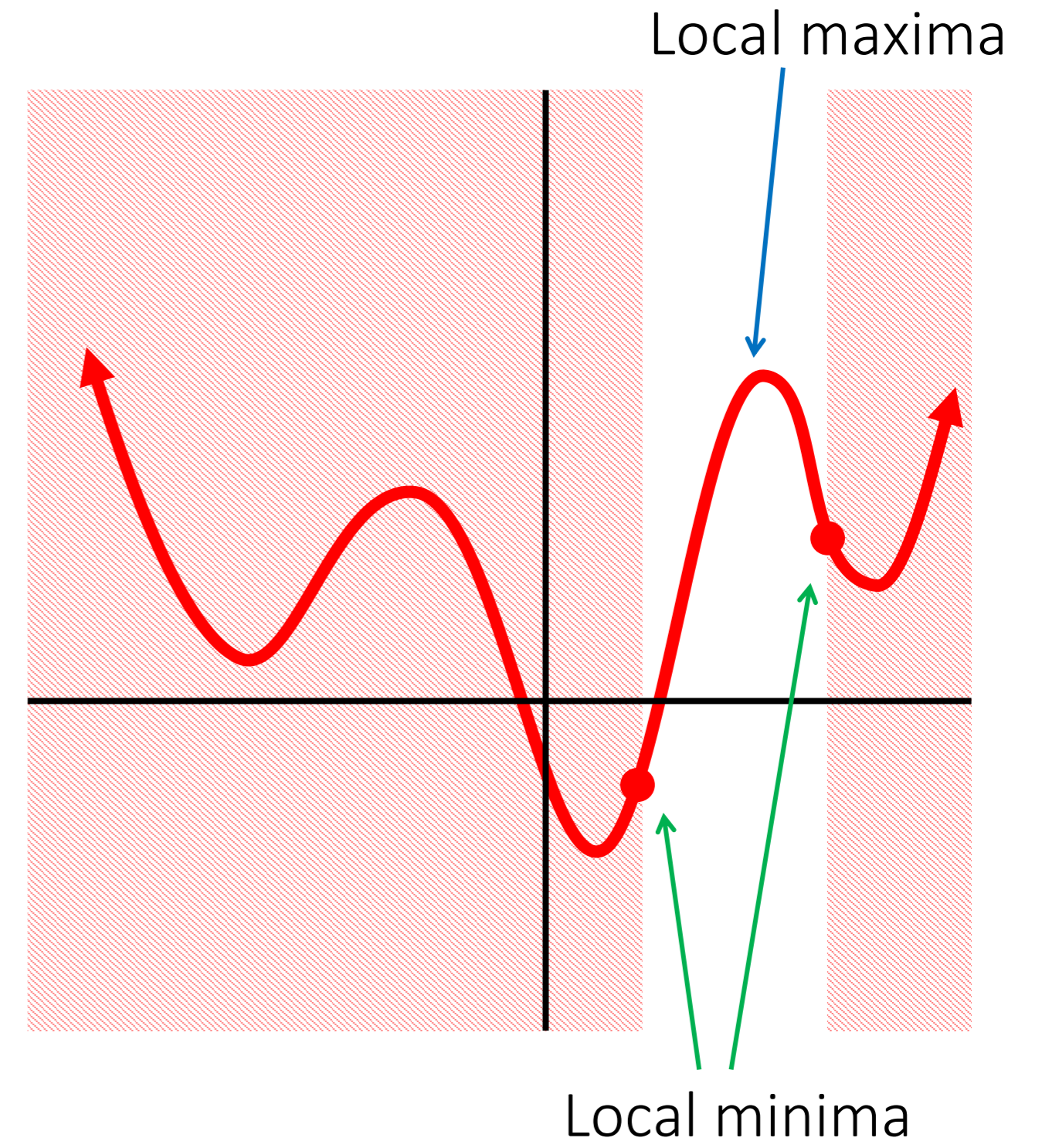
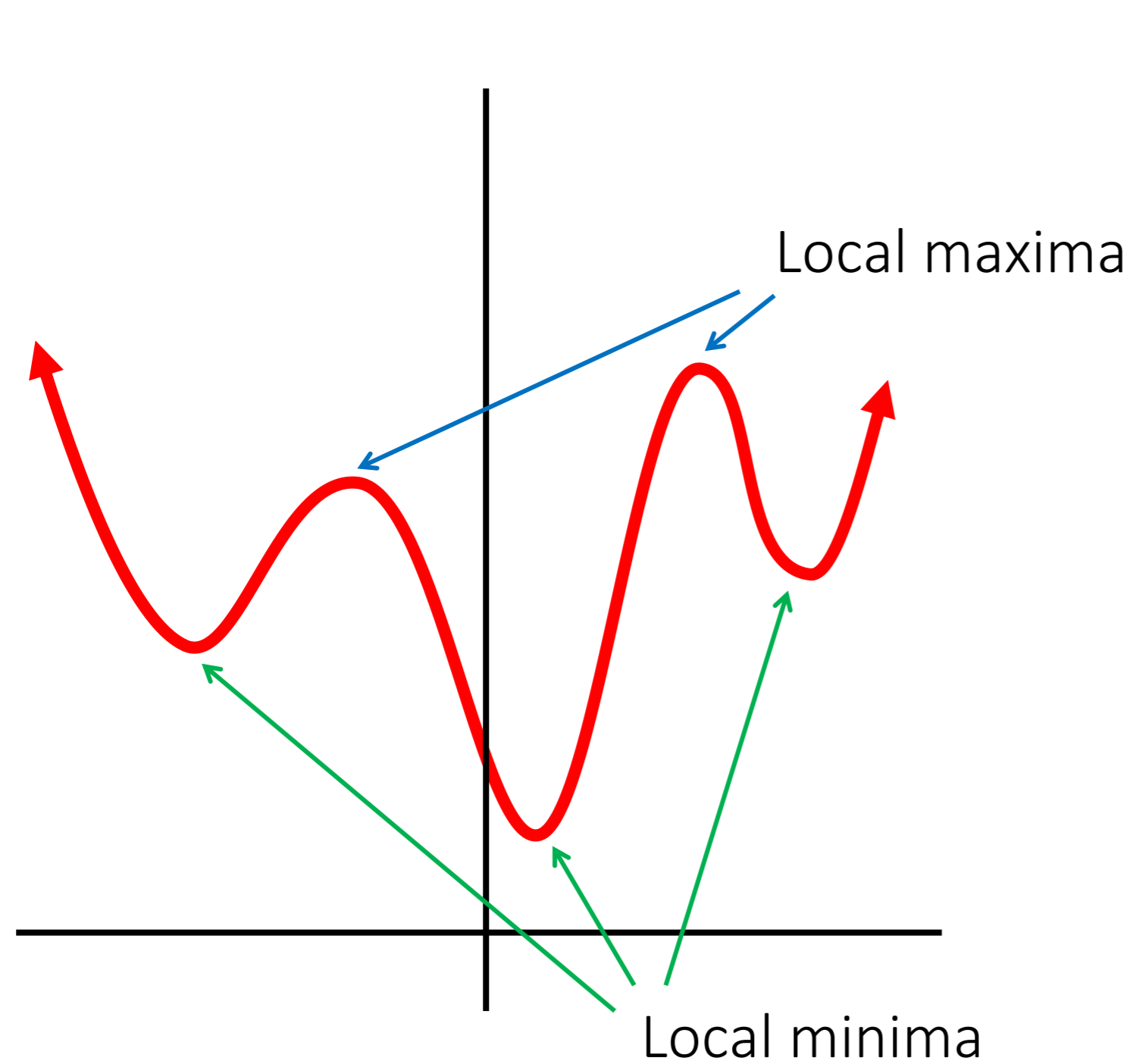
- Objective or cost function $f(\mathbf{x})$ the quantity we are trying to optimize (maximize or minimize)
- The variables x_1, x_2, \dots, x_n which can be represented in vector form as \mathbf{x} (Note: x_n here does NOT correspond to a point in our dataset)
- Constraints that limit how small or big variables can be. These can be equality constraints, noted as $h_k(\mathbf{x})$ and inequality constraints noted as $g_j(\mathbf{x})$
- An optimization problem is usually expressed as:

$$\begin{aligned} & \max_{\mathbf{x}} f(\mathbf{x}) \\ s. t. & \quad \mathbf{g}(\mathbf{x}) \geq 0 \\ & \quad \mathbf{h}(\mathbf{x}) = 0 \end{aligned}$$

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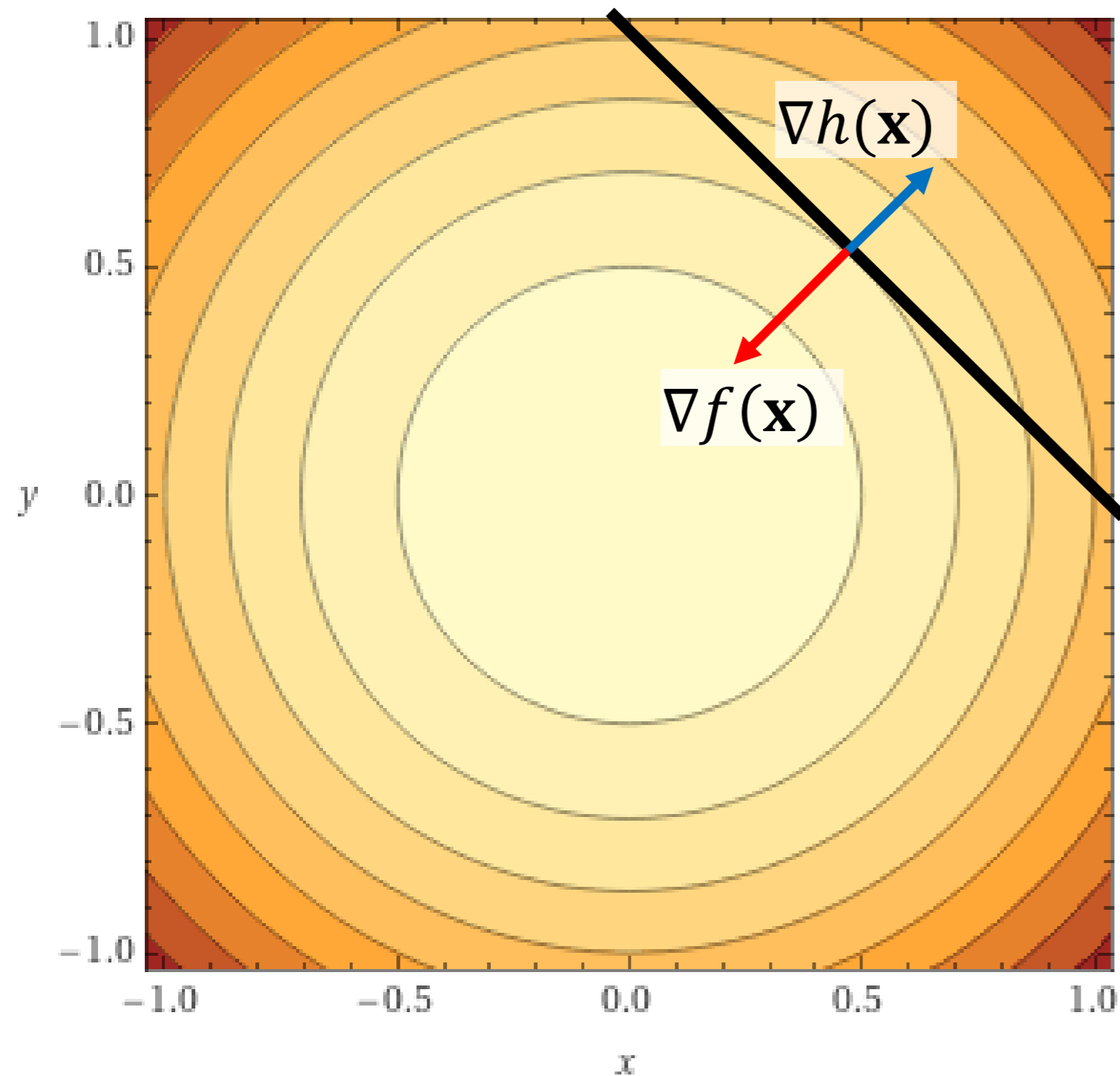
Unconstrained and constrained optimization



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- Unconstrained optimization
- Constrained optimization
- **Lagrange multipliers and KKT conditions**
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Lagrangian multipliers: equality constraint



$$\begin{aligned} \max_{\mathbf{x}} \quad & 1 - x_1^2 - x_2^2 \\ \text{s.t.} \quad & x_1 + x_2 - 1 = 0 \end{aligned}$$

Objective function: $f(x_1, x_2) = 1 - x_1^2 + x_2^2$

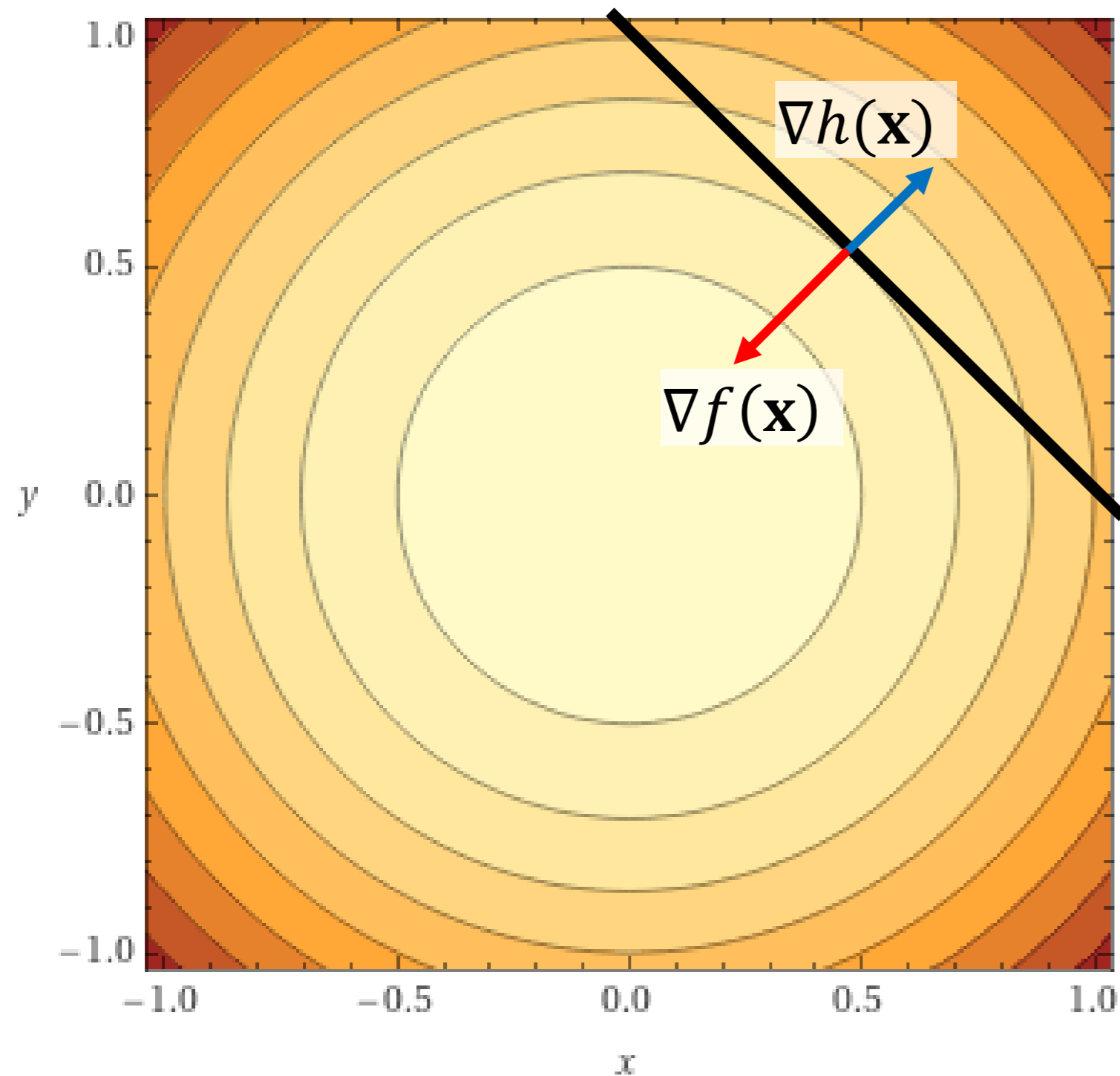
Equality constraint: $h(x_1, x_2) = x_1 + x_2 - 1 = 0$

Intuition: $\nabla f(\mathbf{x}) + \mu \nabla h(\mathbf{x}) = 0$

Lagrangian: $L(\mathbf{x}, \mu) = f(\mathbf{x}) + \mu h(\mathbf{x}) = 0$
 $\text{s.t.} \quad \mu \neq 0$

Solve $\nabla L(\mathbf{x}, \mu)$

Lagrangian multipliers: equality constraint



$$L(\mathbf{x}, \mu) = 1 - x_1^2 + x_2^2 + \mu(x_1 + x_2 - 1)$$

$$\frac{\partial L}{\partial x_1} = -2x_1 + \mu = 0$$

$$\frac{\partial L}{\partial x_2} = -2x_2 + \mu = 0$$

$$\frac{\partial L}{\partial \mu} = x_1 + x_2 - 1 = 0$$

$$\text{Solution: } x_1, x_2, \mu = \left(\frac{1}{2}, \frac{1}{2}, 1\right)$$

Lagrangian multipliers

- Maximization problem

$$\begin{aligned} \max_{\mathbf{x}} f(\mathbf{x}) \\ \text{s.t. } g(\mathbf{x}) \geq 0 \\ h(\mathbf{x}) = 0 \end{aligned}$$

- Lagrangian function:

$$L(\mathbf{x}, \lambda, \mu) = f(\mathbf{x}) + \lambda g(\mathbf{x}) + \mu h(\mathbf{x})$$

- KKT conditions:

$$\begin{aligned} g(\mathbf{x}) &\geq 0 \\ \lambda &\geq 0 \\ \lambda g(\mathbf{x}) &= 0 \\ \mu &\neq 0 \end{aligned}$$

- Minimization problem

$$\begin{aligned} \min_{\mathbf{x}} f(\mathbf{x}) \\ \text{s.t. } g(\mathbf{x}) \geq 0 \\ h(\mathbf{x}) = 0 \end{aligned}$$

- Lagrangian function:

$$L(\mathbf{x}, \lambda, \mu) = f(\mathbf{x}) - \lambda g(\mathbf{x}) + \mu h(\mathbf{x})$$

- KKT conditions:

$$\begin{aligned} g(\mathbf{x}) &\geq 0 \\ \lambda &\geq 0 \\ \lambda g(\mathbf{x}) &= 0 \\ \mu &\neq 0 \end{aligned}$$

Solve the optimization problem by resolving: $\nabla L = 0$

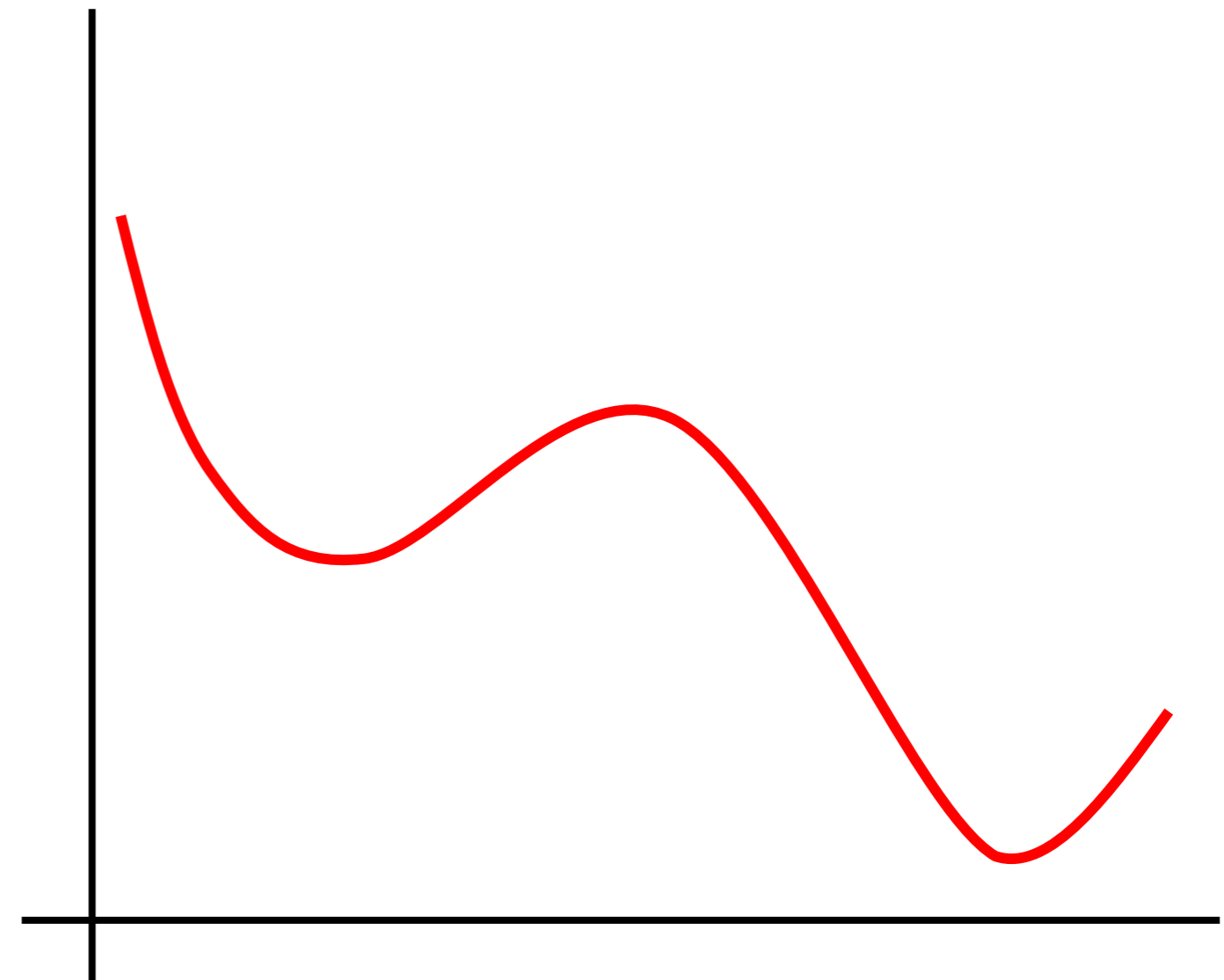
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- **Gradient descent**

Gradient descent

- Common in machine learning problems when not all of the data is available immediately or a closed form solution is computationally intractable
- Iterative minimization technique for differentiable functions on a domain

$$\mathbf{x}_{n+1} = \mathbf{x}_n - \gamma \nabla F(\mathbf{x}_n)$$



Gradient descent: Himmelblau's function

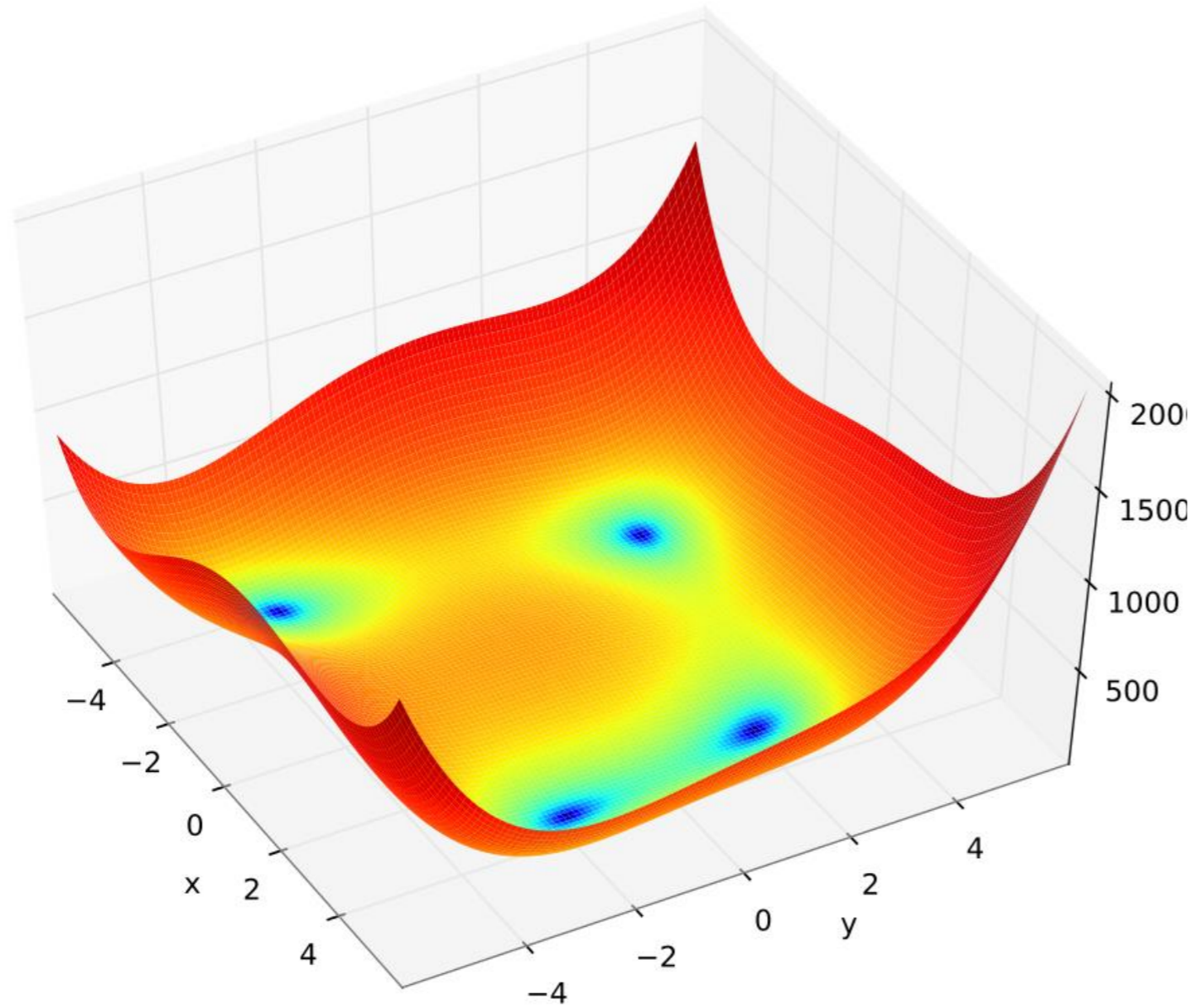


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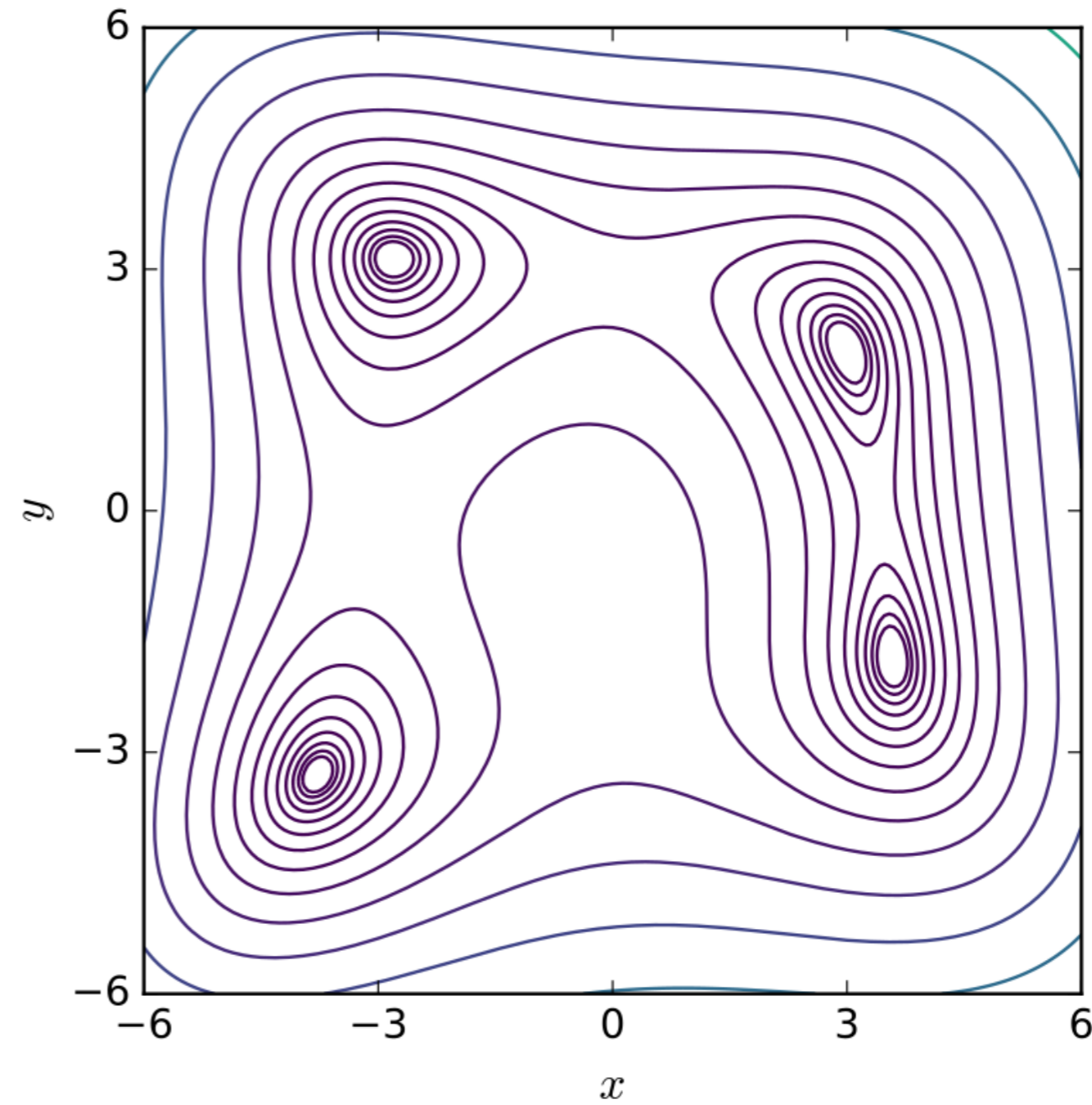


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