The week ahead

- Quiz 1, mean is 76% and average completion time 6.26 min
- Assignment 1 Early bird special \rightarrow 2 complete questions by Wednesday, Sep 2nd
- Second round of project seminars, available Thursday, Aug 3rd
- Open office hours on Thursday, 7pm to 8pm
 - https://primetime.bluejeans.com/a2m/live-event/qfsqxjec
- Quiz 2, Friday, Sep 4th 6am until Sep 5th 6am
 - Information theory and optimization

Coming up soon

- Labor day, Sep $7^{th} \rightarrow NO$ CLASS
- Project team composition due Sep 8th
- Assignment 1 due Sep 9th

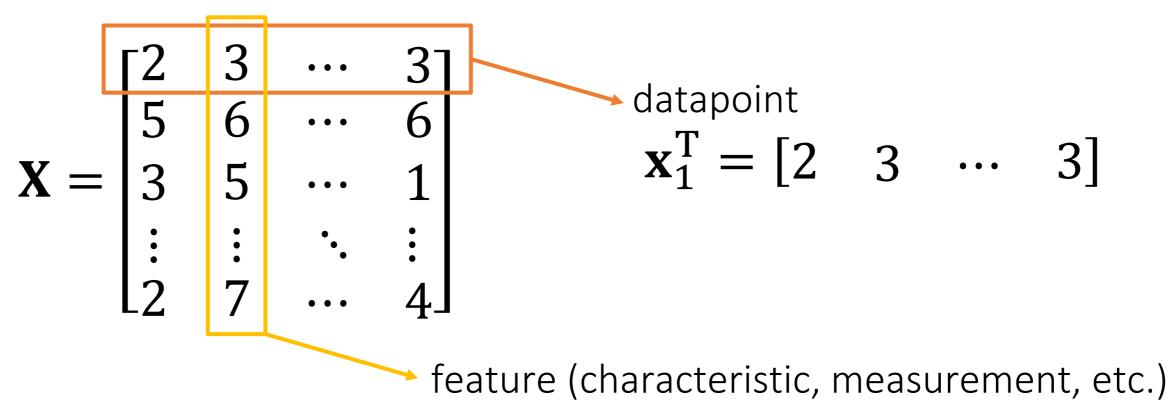
CS4641B Machine Learning Highlights: Linear algebra and probability theory

Rodrigo Borela ► rborelav@gatech.edu



Linear algebra

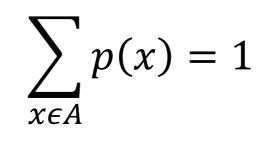
- Norms: measuring vector lengths
- **Covariance and correlation:** understanding relationships between features
- SVD: data compression and dimensionality reduction



Probability theory

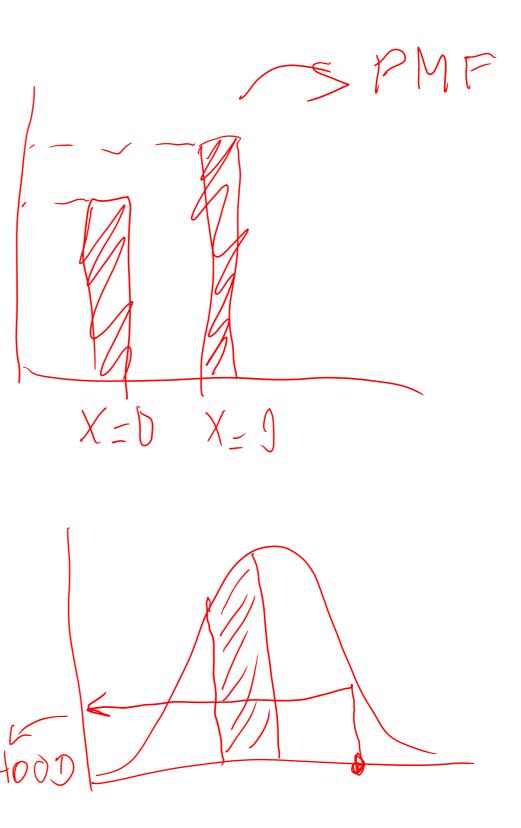
Discrete variable

- Example: Coin flip (integer)
- Discrete probability distribution (e.g. Bernoulli)
- Probability mass function
- Probability value

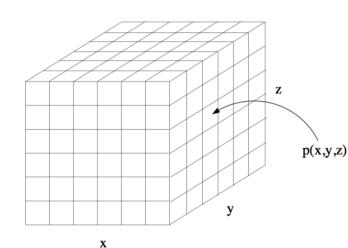


- Continuous variable
 - Example: Temperature (real number)
 - Continuous probability distribution (e.g. Gaussian)
 - Probability density function
 - Density or likelihood value

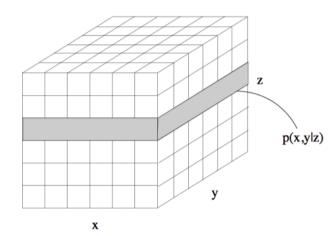
p(x)dx = 1



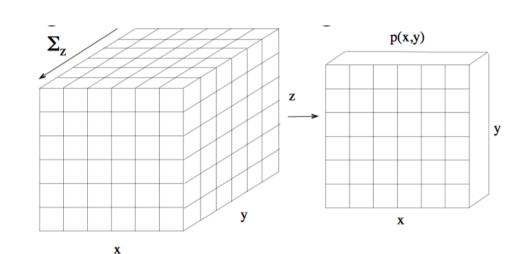
Joint, conditional and marginal distribution



Joint distribution p(x, y) = p(X = x and Y = y), from the product rule p(x, y) = p(x|y)p(y)



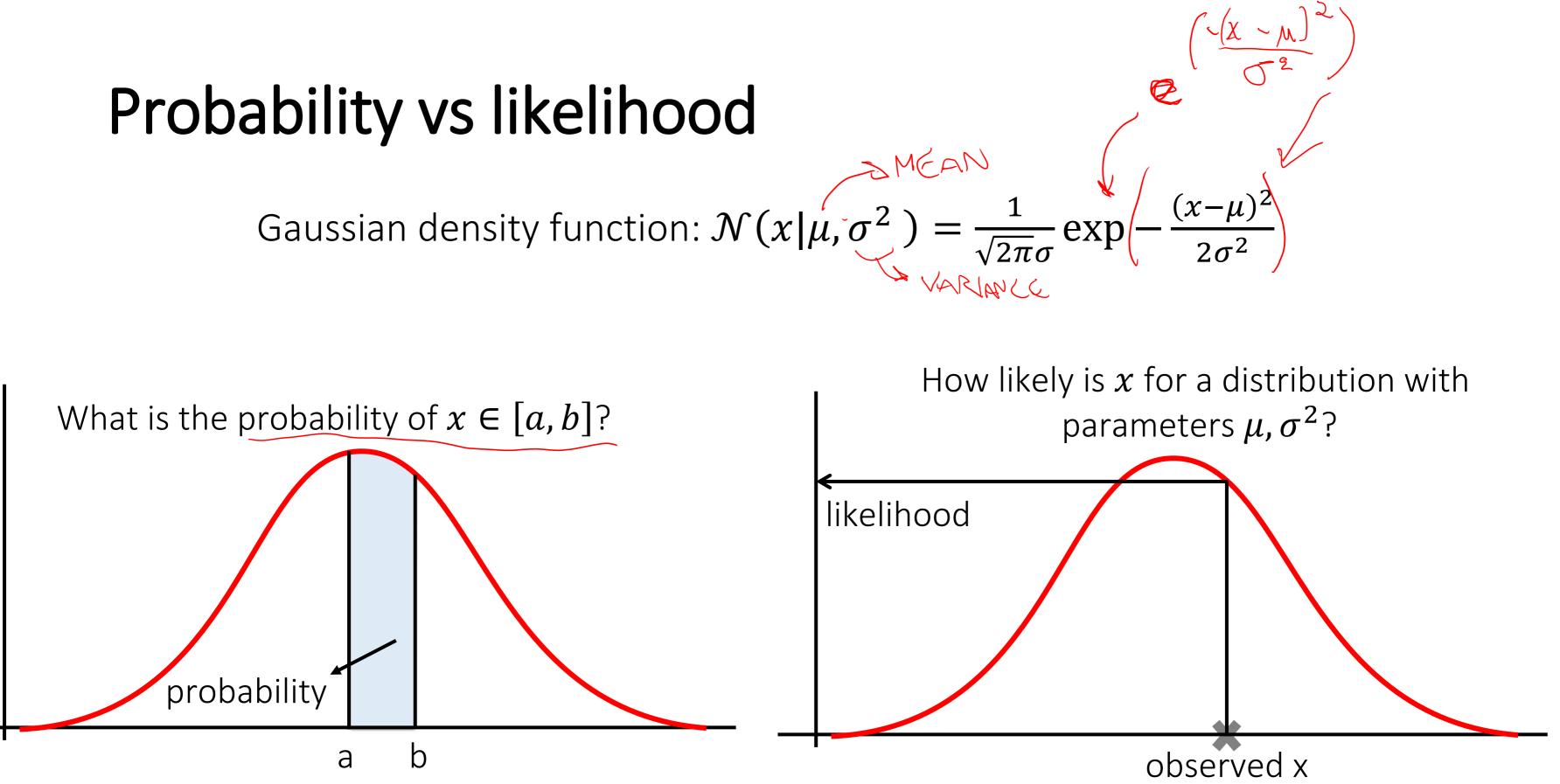




Marginal distribution

p(x) = p(X = x), from the sum rule $p(x) = \sum_{y} p(x, y)$

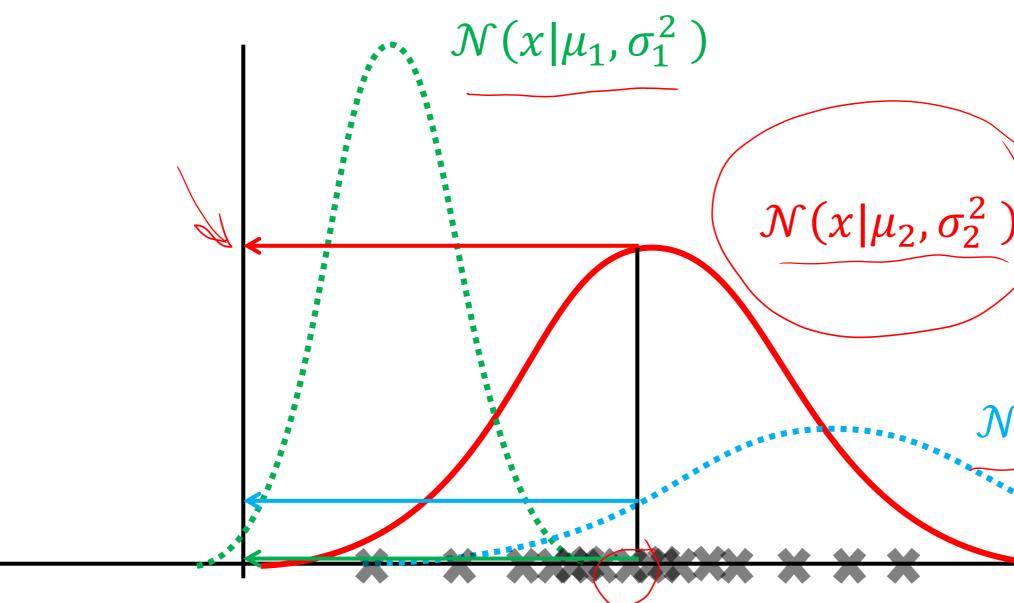
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Maximum likelihood estimation

What are the parameters that best explain the data I have observed?



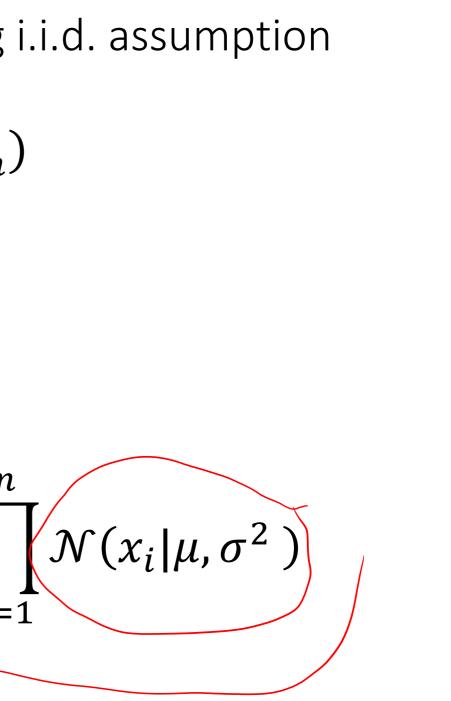
 $\mathcal{N}(x|\mu_3,\sigma_3^2)$

Maximum likelihood estimation

1. Write the likelihood function for our dataset using i.i.d. assumption

$$L(\mathcal{D} \mid \theta) = p(x_1, x_2, x_3, \dots, x_n)$$

applying the i.i.d. assumption $\lim_{x \in L \setminus A \cup OD} X_1$ $p_{ATASET} = p(x_1)p(x_2) \dots p(x_n)$ $\int_{n} \int_{n} \int_{n} f(x_i | \theta) \to L(D | \mu, \sigma^2) = \prod_{i=1}^{n} \mathcal{N}(x_i | \mu, \sigma^2)$ $\int_{n} \mathcal{P} \cap B \text{ DeNsity}$ FUNCTION

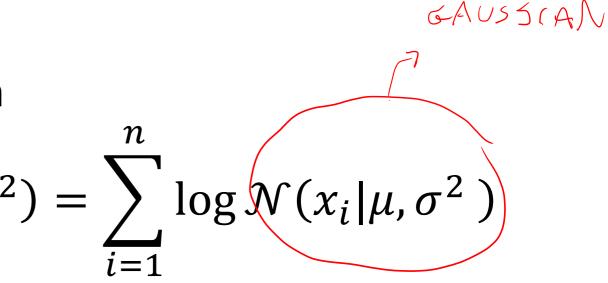


Maximum likelihood estimation

2. Compute the logarithm to of the likelihood function $logL(\mathcal{D}|\theta) = l(\mathcal{D}|\theta) = \sum_{i=1}^{n} \log f(x_i|\theta) \to l(\mathcal{D}|\mu, \sigma^2) = \sum_{i=1}^{n} \log \mathcal{N}(x_i|\mu, \sigma^2)$

3. Maximize the log-likelihood with respect to each parameter

 $\frac{\partial l}{\partial \mu} = 0 \rightarrow \mu_{ML} \text{ (the mean that maximizes the likelihood)}$ $\frac{\partial l}{\partial \sigma^2} = 0 \rightarrow \sigma_{ML}^2 \text{ (the variance that maximizes the likelihood)}$



CS4641B Machine Learning Lecture 05: Information theory

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These slides are based on slides from Le Song, Roni Rosenfeld, Chao Zhang, and Maneesh Sahani and Mahdi Roozbahani



Outline

- Motivation
- Entropy
- Conditional Entropy and Mutual Information
- Cross-Entropy and KL-Divergence

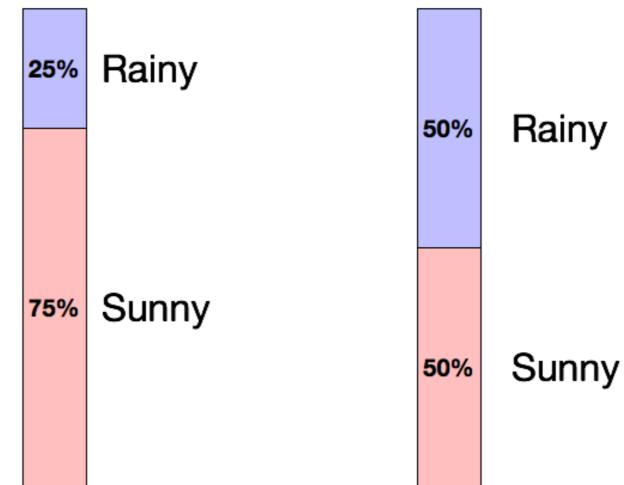
Outline

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Uncertainty and Information

- Information is processed data whereas knowledge is information that is modeled to be useful.
- You need information to be able to get knowledge Data/fact \rightarrow information \rightarrow knowledge
- **Information** ≠knowledge Concerned with abstract possibilities, not their meaning

Uncertainty and Information



Which day is more uncertain? How do we relate uncertainty and information?

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Information

- Define a measure of information based on the probability of an event happening
- More information when an unlikely event occurs than when something certain occurs (in fact, it should be zero when the event is certain)
- **Example:** You are in beautiful Los Angeles, California and you are told it did not rain yesterday \rightarrow not a lot of information since it rarely rains in SoCal
- We can associate our measure of information with probability of an event occurring. Let X be a random variable with distribution p(x) = p(X = x):

$$I(x) = h(x) = -\log_2 p(x)$$
INFORMATION NEORMATION

THIS IS POSITIVE

INFORMATION PROBABILITY

Example: is a picture worth 1,000 words?

Information obtained by a random word from a 100,000 word vocabulary:

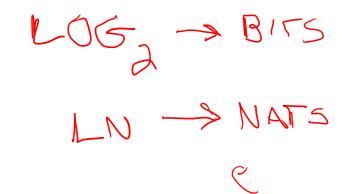
$$I(word) = -\log_2\left(\frac{1}{p(x)}\right) = \log\left(\frac{1}{1/100,000}\right)$$

- A 1,000-word document from same source: $I(document) = 1000 \times I(word) = 16610 \text{ bits}$
- A 640 x 480 pixel, 16-greyscale picture (each pixel has 16 bits information):

$$I(picture) = \log_2\left(\frac{1}{1/16^{640 \times 480}}\right) = 1,228,$$

HOW YOU A picture is worth (a lot more than) 1,000 words! #shook INTENSITIES

= 16.61 *bits*



,800 *bits*

Motivation: compression

- Suppose we observe a sequence of events
 - Coin tosses
 - Words in a language
 - Notes in a song
 - etc.
- We want to record the sequence of events in the smallest possible space
- In other words we want the shortest representation which preserves the information
- Another way to think about this: how much information does the sequence of events actually contain?

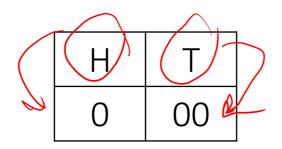
possible space h preserves the information **oes the sequence of events**

Example: compression

Consider the problem of recording coin tosses in unary



Approach 1:



00, 00, 00, 00, 0

We used **9** characters

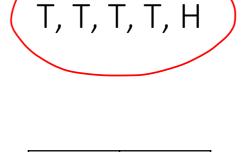
- Which one has a higher probability: T or H? TAIL 5
- Which one should carry more information: T or H?

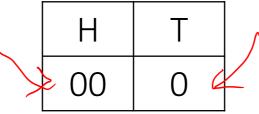
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Example: compression

Consider the problem of recording coin tosses in unary

Approach 2:





0, 0, 0, 0, 00

We used **6** characters

- Which one has a higher probability: T or H? τ
- Which one should carry more information: T or H?

Motivation: Compression

- Frequently occurring events should have short encodings
- We see this in English with words such as "a", "the", "and", etc.
- We want to maximize the information-per-character
- Seeing common events provides little information
- Seeing uncommon events provides a lot of information

Outline

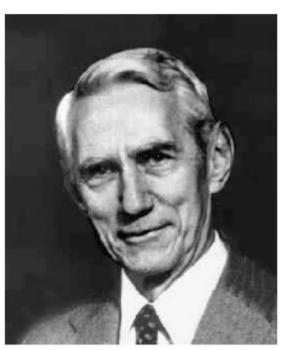
Motivation

Entropy

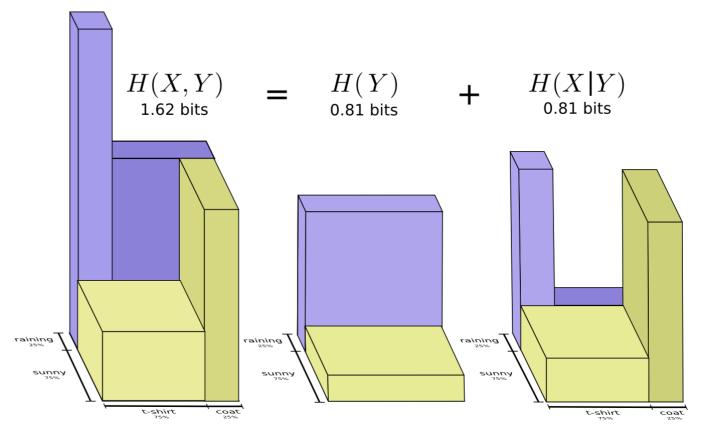
- Conditional entropy and mutual information
- Cross-Entropy and KL-Divergence

Information Theory

- Information theory is a mathematical framework which addresses questions like:
 - How much information does a random variable carry about?
 - How efficient is a hypothetical code, given the statistics of the random variable?
 - How much better or worse would another code do?
 - Is the information carried by different random variables complementary or redundant?



Claude Shannon



ddresses questions like: bout? s of the random variable?

Entropy

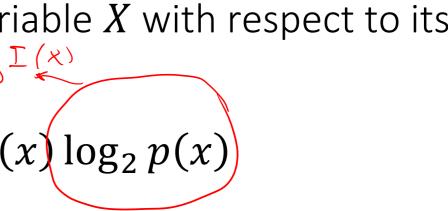
• Average amount of information to encode a random variable X with respect to its distribution p(x) is the entropy H(x):

$$H(x) = E[h(x)] = \sum_{x} h(x)p(x) = -\sum_{x} p(x)$$

Considering a random variable X with k possible states:

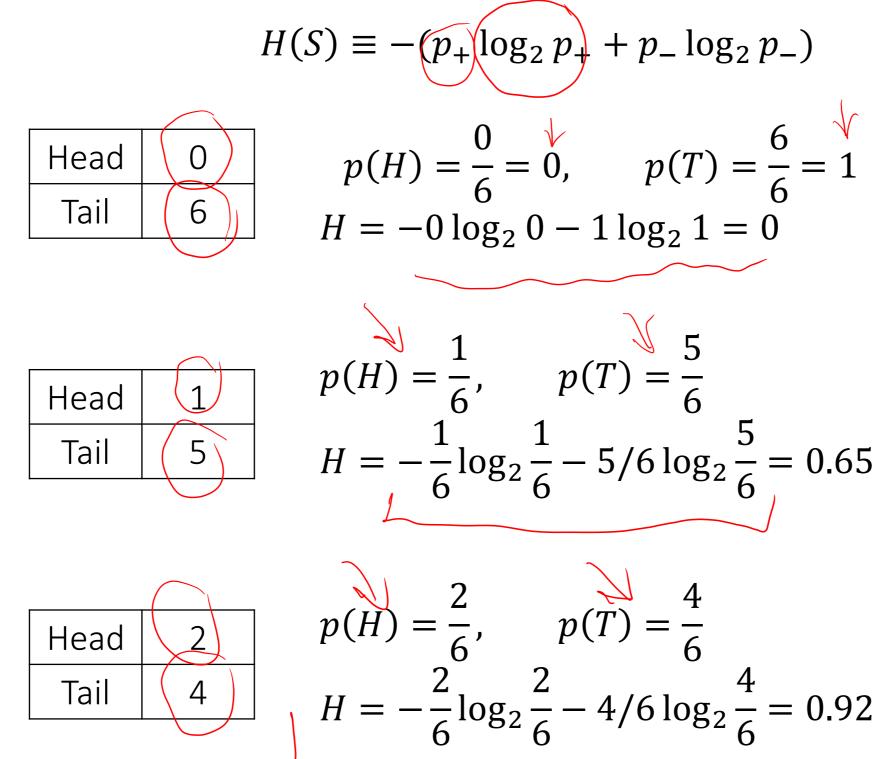
$$H(x) = -\sum_{k=1}^{K} p(x=k) \log_2 p(x=k) = \sum_{k=1}^{K} p(x=k) \log_2 \frac{1}{p(x=k)}$$

- Information theory:
 - Most efficient code assigns $-\log_2 P(x=k)$ bits to encode the message x=k.



code the message x = k.

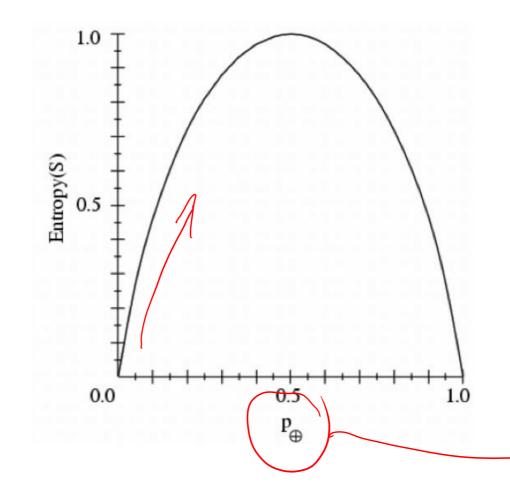
Example: entropy computation

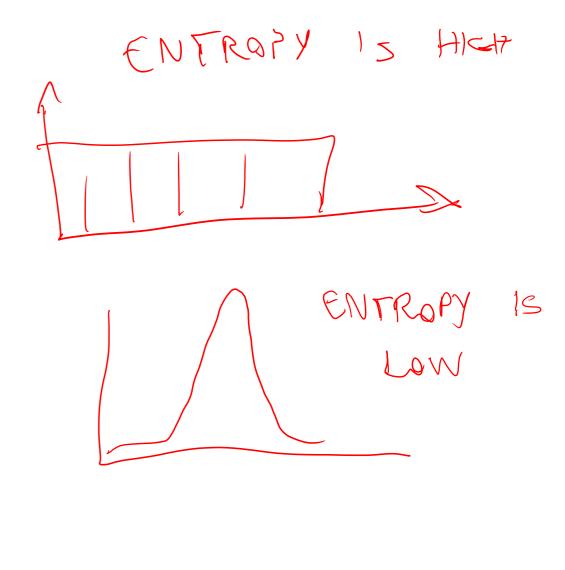


Example: entropy

- *S* is a sample of coin flips
- p_+ is the proportion of heads in S
- p_{-} is the proportion of tails in S
- Entropy measures the uncertainty of S

 $H(S) \equiv -(p_{+} \log_2 p_{+} + p_{-} \log_2 p_{-})$





 $(P = 1 - P^{+})$ DT 25

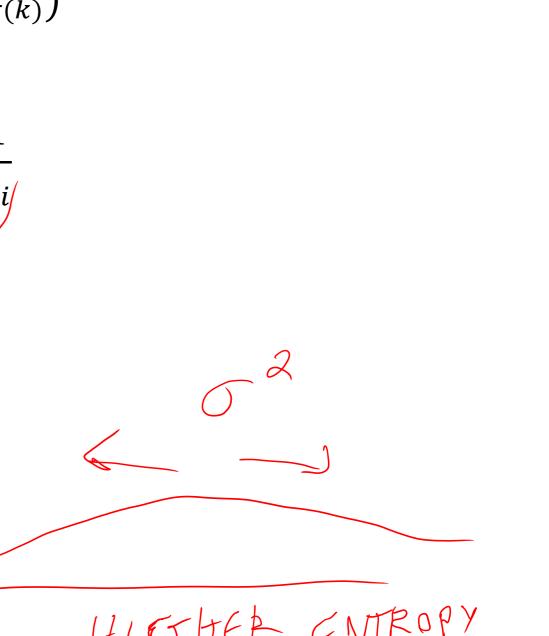
Properties of Entropy

- Non-negative: $H(P) \ge 0$
- Invariant with respect to permutation of its inputs:

 $H(p_1, p_2, \dots, p_k) = H(p_{\tau(1)}, p_{\tau(2)}, \dots, p_{\tau(k)})$

- For any other probability distribution $\{q_1, q_2, ..., q_k\}$ $H(P) = \sum_i p_i \log \frac{1}{p_i} < \sum_i p_i \log \frac{1}{q_i}$
- $H(P) \le \log_2 k$, with equality iff $p_i = \frac{1}{k}$, $\forall i$
- The further *P* is from uniform, the lower the entropy

LOWER

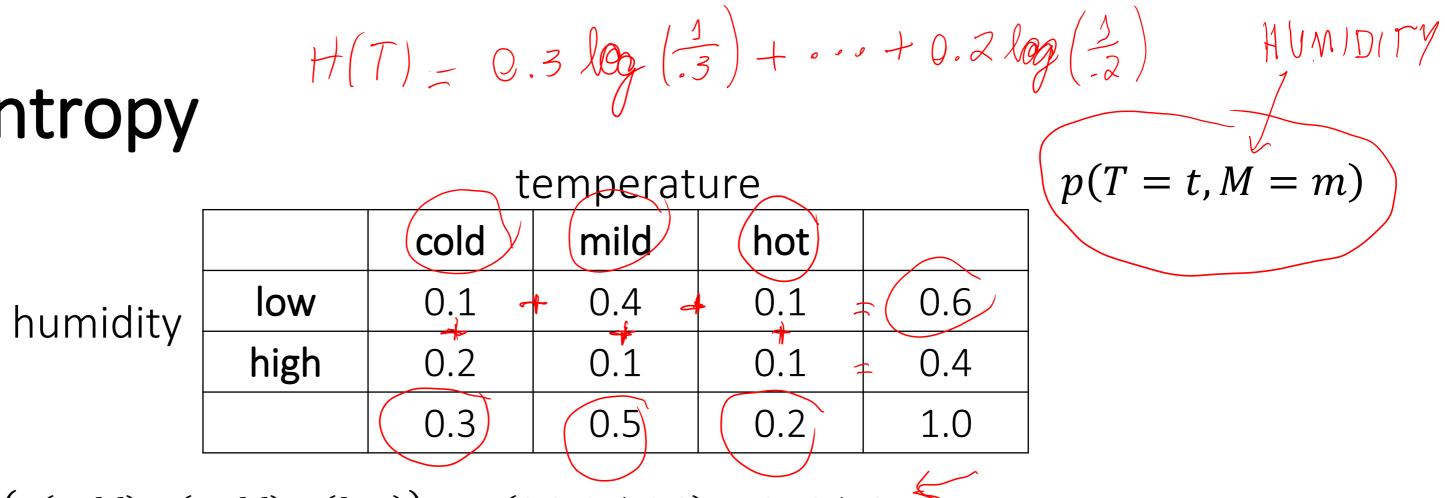


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Outline

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Joint Entropy



- H(T) = H(p(cold), p(mild), p(hot)) = H(0.3, 0.5, 0.2) = 1.48548
- H(M) = H(p(low), p(high)) = H(0.6, 0.4) = 0.970951

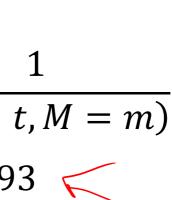
•
$$H(T) + H(M) = 2.456431 \iff$$

Joint entropy: consider the space of (t, m) events:

$$H(T,M) = \sum_{t,m} p(T = t, M = m) \cdot \log_2 \frac{1}{P(T = m)}$$

$$H(0.1, 0.4, 0.1, 0.2, 0.1, 0.1) = 2.3219$$

Notice that H(T, M) < H(T) + H(M). Does it make sense!?



MARGINALIZING OVER M.

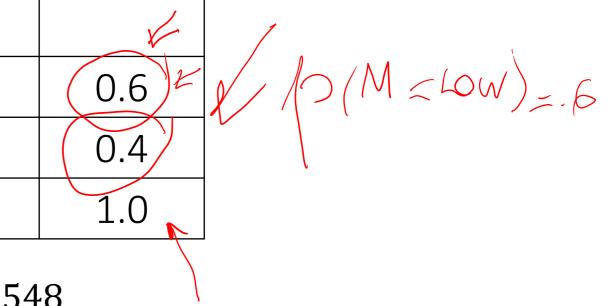
Joint Entropy temperature mild cold hot 0.1 low 0.4 0.1 humidity high 0.2 0.1 0.1 0.5 0.2 0.3 H(T) = H(p(cold), p(mild), p(hot)) = H(0.3, 0.5, 0.2) = 1.48548H(M) = H(p(low), p(high)) = H(0.6, 0.4) = 0.970951H(T) + H(M) = 2.456431Joint entropy: consider the space of (t, m) events: $H(T, M) = \sum_{\substack{t,m \\ H(0.1, 0.4, 0.1, 0.2, 0.1, 0.1)}} p(T = t, M = m) \cdot \log_2 \frac{1}{P(T = t)}$ Notice that H(T, M) < H(T) + H(M). Does it make sense!?

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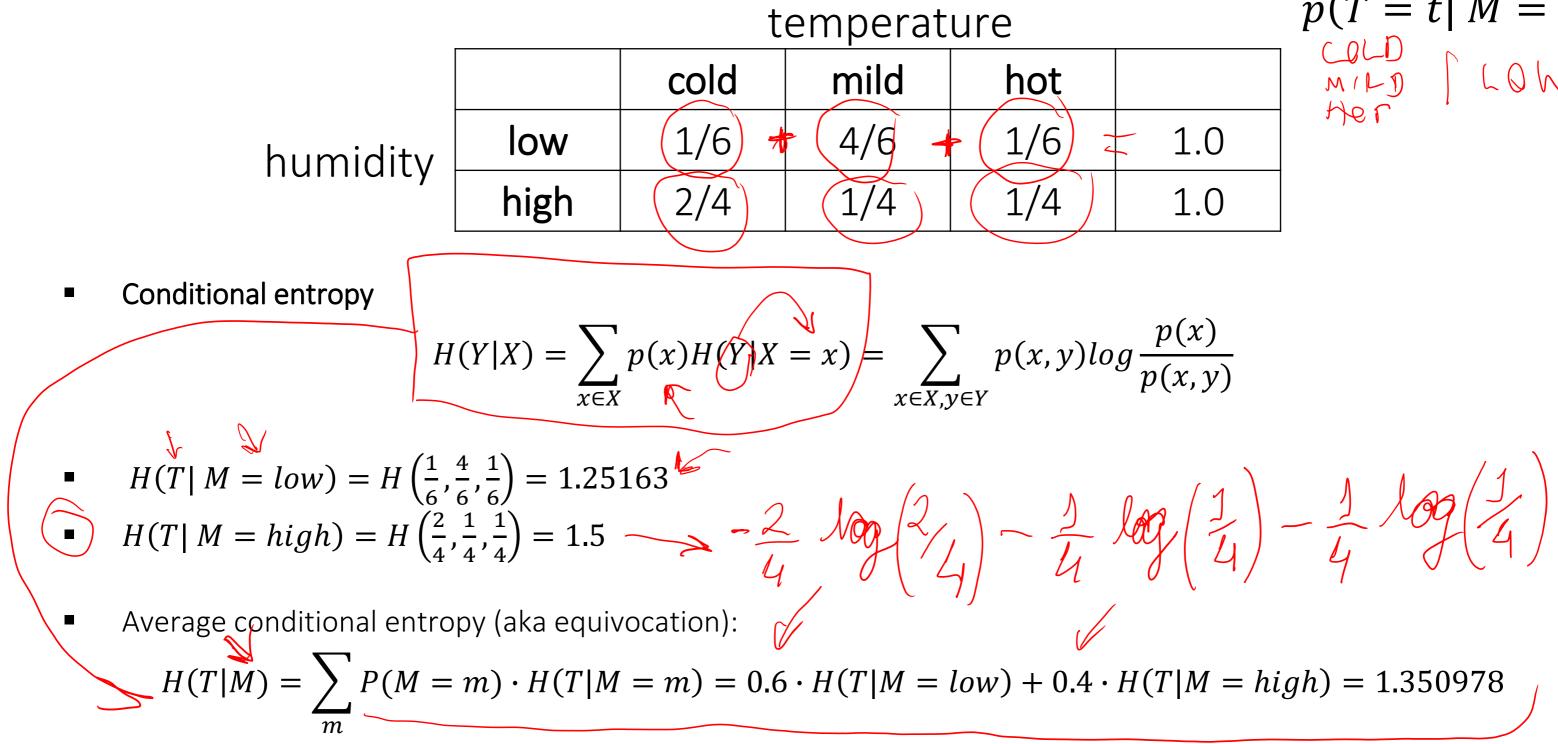
JOINT DISTRIB

p(T = t, M = m)



$$\frac{1}{t, M = m}$$

Conditional Entropy



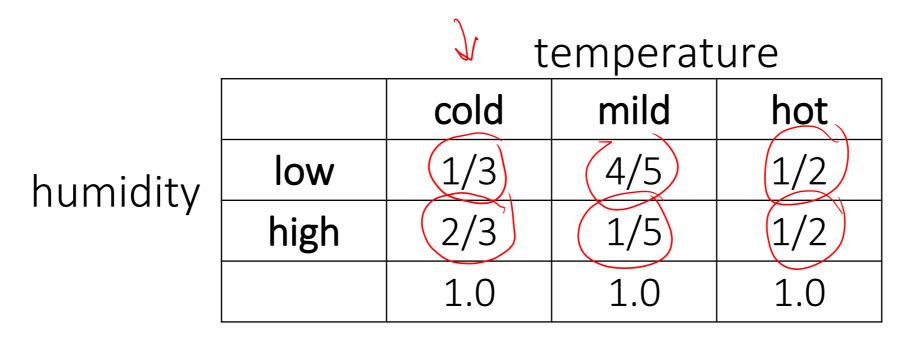
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CONDITIONAL DIST

4	1.0
	1.0

 $p(T = t \mid M = m)$ MILD LOW OR AKH

Conditional Entropy



Conditional entropy

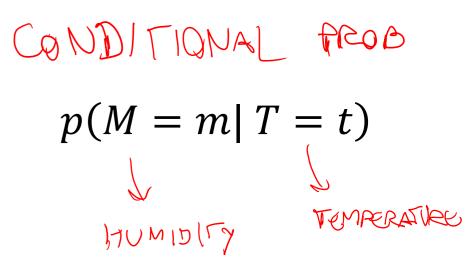
•
$$H(M|T = cold) = H\left(\frac{1}{3}, \frac{2}{3}\right) = 0.918296$$

•
$$H(M|T = mild) = H\left(\frac{4}{5}, \frac{1}{5}\right) = 0.721928$$

•
$$H(M|T = mild) = H\left(\frac{1}{2}, \frac{1}{2}\right) = 1.0$$

Average conditional entropy (aka equivocation): $H(M|T) = \sum_{t} P(T = t) \cdot H(M|T = t) = 0.3 \quad H(M|T = cold) + 0.5 \quad H(M|T = mild) + 0.2 \cdot H(M|T = hot)$ = 0.8364528 $P(T = 0.1) \quad P(T = MLP) \quad P(T = HP)$

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Conditional Entropy

- Conditional entropy H(Y|X) of a random variable Y given x_i
 - Discrete random variables $\int H(Y|X) = \sum_{x \in X} p(x_i) H(Y|X = x_i) = \sum_{x \in X, y \in Y} p(x_i, y_i) \log \frac{p(x_i)}{p(x_i, y_i)}$
- Continuous random variable

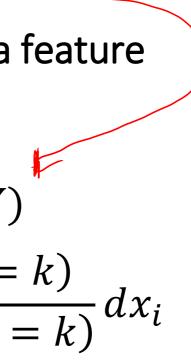
$$\int H(Y|X) = -\int \left(\sum_{k=1}^{K} p(y=k|x_i) \log_2 p(y=k|x_i)\right) \log_2 p(y=k|x_i) \log_2 p(y=$$

POSSIBLE STATES

 $(k) \int p(x_i) dx_i$

Mutual Information

- Mutual information: quantify the reduction in uncertainty in Y after seeing feature X I(X,Y) = (H(Y)) - H(Y|X)
- The more the reduction in entropy, the more informative a feature
- Mutual information is symmetric I(X,Y) = I(Y,X) = H(X) - H(X|Y) $I(X, Y) = \int \sum_{i=k}^{K} p(x_i, y = k) \log_2 \frac{p(x_i, y = k)}{p(x_i)p(y = k)} dx_i$ $= \int \sum_{i=1}^{n} p(x_i, y = k) \log_2 \frac{p(x_i | y = k)}{p(x_i)} dx_i$



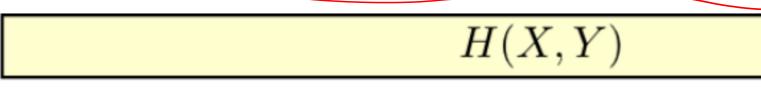
Properties of mutual information

$$(X,Y) = H(X) - H(X|Y) = \sum_{x} p(x) \cdot \log \frac{1}{p(x)} - \sum_{x,y} \frac{1}{p(x)} - \sum_{x,y} p(x,y) \cdot \log \frac{p(x|y)}{p(x)} = \sum_{x,y} p(x,y) \cdot \log \frac{p(x|y)}{p(x)} = \sum_{x,y} p(x,y) \cdot \log \frac{p(x,y)}{p(x)} = \sum_{x,y} p($$

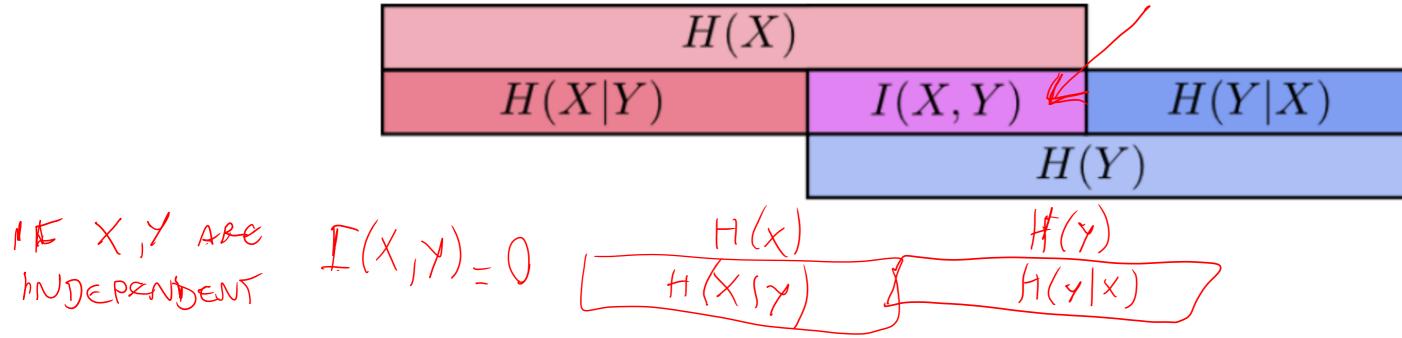
- Properties of average mutual information:
 - Symmetric (but $H(X) \neq H(Y)$ and $H(X|Y) \neq H(Y|X)$
 - Non-negative (but H(X) H(X|Y) may be negative)
 - Zero iff X, Y independent

 $\sum_{x,y} p(x,y) \cdot \log \frac{1}{p(x|y)}$ $\log \frac{p(x,y)}{p(x)p(y)}$

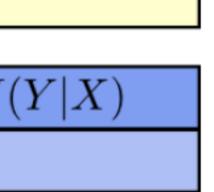




H(X)		H
H(X Y)	H(Y)	



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 $\begin{array}{l} \downarrow \\ \downarrow (x, y) = H(x) \\ + H(y|x) \end{array} \end{array}$

Image Credit: Christopher Olah.

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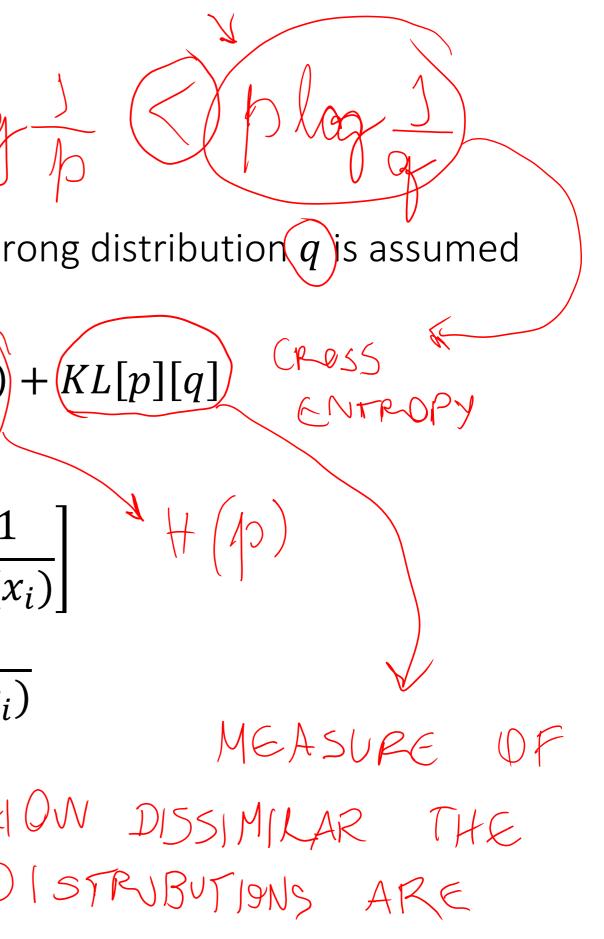
Cross Entropy

Cross Entropy: The expected number of bits when a wrong distribution (q) is assumed while the data actually follows a distribution p

$$H(p,q) = -\sum_{x \in X} p(x) \log q(x) = H(p) +$$

This is because

$$H(p,q) = E_p[l_i] = E_p\left[\log\frac{1}{q(x_i)}\right]$$
$$H(p,q) = \sum_{x_i} p(x_i)\log\frac{1}{q(x_i)}$$



Kullback-Leibler Divergence

Another useful information theoretic quantity measures the difference between two distributions

$$-KL[p][q] = \sum_{x} p(x) \log \frac{q(x)}{p(x)}$$
$$\sum_{x} p(x) \log \frac{q(x)}{p(x)} \le \log \sum_{x} p(x) \frac{q(x)}{p(x)}$$
$$\log \sum_{x} q(x) = \log 1 = 0 \quad \underline{By}$$
$$So \ KL[p][q] \ge 0. \text{ Equality iff } p = q, \ KL[p][q] = 0$$

<u>Jensen Inequality</u> $E[g(x)] \le g(E[x])$ $g(x) = \log(x)$